First-order structures

Double velocities

The double group

Double structures and jets

D.J. Saunders

In honour of W. M. Tulczyjew June 2011

First-order structures

Double velocities

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Abstract

Double vector bundles, of which the double tangent bundle is a standard example, were introduced by Pradines in 1968.

In this talk I shall discuss how certain double vector bundles and other double structures can be used in the construction of jet bundles. $\underset{\circ \bullet}{\text{Introduction}}$

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An elementary observation

Consider a real vector space V, of finite dimension n + 1.

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An elementary observation

Consider a real vector space V, of finite dimension n + 1.

If $\alpha \in V^*$ is non-zero then

$$A_{\alpha} = \{ v \in V : \alpha(v) = 1 \}$$

is an n-dimensional affine space.

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The group of non-zero real numbers acts on $V - \{0\}$ by multiplication, with quotient PV, an n-dimensional projective space.

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We regard $A_{\alpha} \subset PV$ by $v \mapsto [v]$.

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We regard $A_{\alpha} \subset PV$ by $v \mapsto [v]$.

The fibrations found in several jet structures are related in much the same way as V, A_{α} and PV

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First-order velocities

Manifold *E*; connected open $O \subset \mathbb{R}^m$ with $0 \in O$ '*m*-curve' $\gamma : O \to E$



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First-order velocities

Manifold *E*; connected open $O \subset \mathbb{R}^m$ with $0 \in O$ '*m*-curve' $\gamma : O \rightarrow E$

m-velocity manifold

$$T_m E = \{j_0 \gamma : \gamma \text{ an } m\text{-curve}\}$$

projection map

$$\tau_{mE}: T_mE \to E$$
, $\tau_{mE}(j_0\gamma) = \gamma(0)$

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Alternative descriptions:

$$T_m E = \bigoplus_E^m T E$$

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$$T_m E = \bigoplus_E^m T E = T E \otimes_E \mathbb{R}^{m*}$$

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Regular first-order velocities

submanifold of regular *m*-velocities

$$\overset{\circ}{T}_{m}E = \{ j_{0}\gamma \in T_{m}E : \gamma \text{ an immersion} \}$$
$$\overset{\circ}{\tau}_{mE} = \tau_{mE}|_{\overset{\circ}{T}_{m}E} : \overset{\circ}{T}_{m}E \to E$$

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Regular first-order velocities

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The prolongation of $f : E_1 \rightarrow E_2$,

$$T_m f: T_m E_1 \to T_m E_2$$
, $T_m f(j_0 \gamma) = j_0 (f \circ \gamma)$

need not restrict to a map $\mathring{T}_m E \rightarrow \mathring{T}_m E$.

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Regular first-order velocities

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The prolongation of $f : E_1 \rightarrow E_2$,

$$T_m f: T_m E_1 \to T_m E_2, \qquad T_m f(j_0 \gamma) = j_0(f \circ \gamma)$$

need not restrict to a map $\mathring{T}_m E \rightarrow \mathring{T}_m E$. Define

$$\mathring{T}_m^{\mathrm{T}} f = \{ j_0 \gamma \in \mathring{T}_m E_1 : f \circ \gamma \text{ an immersion} \}$$
$$T_m f : \mathring{T}_m^{\mathrm{T}} f \to \mathring{T}_m E_2 .$$

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First-order contact elements

First order jet group

 $L_m = \{j_0\phi : \phi : O \to \phi(O) \subset \mathbb{R}^m \text{ diffeomorphism, } \phi(0) = 0\}$

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First-order contact elements

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 $L_m = \{j_0\phi : \phi : O \to \phi(O) \subset \mathbb{R}^m \text{ diffeomorphism, } \phi(0) = 0\}$

 L_m acts on $T_m E$ on the right,

$$\alpha: L_m \times T_m E \to T_m E, \qquad \alpha(j_0 \phi, j_0 \gamma) = j_0(\gamma \circ \phi)$$

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Action restricts to $L_m \times \mathring{T}_m E \to \mathring{T}_m E$;

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Quotient $J_m E = \mathring{T}_m E / L_m$ is a Hausdorff manifold.

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Projection $\rho : \mathring{T}_m E \to J_m E$ is an open map and a principal L_m -bundle.

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Quotient $J_m E = \mathring{T}_m E / L_m$ is a Hausdorff manifold.

Projection $\rho : \mathring{T}_m E \to J_m E$ is an open map and a principal L_m -bundle.

Define $\pi_{mE}: J_mE \to E$ by $\pi_{mE}([j_0\gamma]) = \gamma(0) = \tau_{mE}(j_0\gamma)$.

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First-order jets of sections

 $\pi: E \to M$ fibration



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First-order jets of sections

 $\pi: E \to M$ fibration

$$\mathring{T}_m^{\mathrm{T}} \pi = \{ j_0 \gamma : \pi \circ \gamma \text{ an immersion} \} \subset \mathring{T}_m E$$

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First-order jets of sections

$\pi: E \to M$ fibration

 $\mathring{T}_m^{\mathrm{T}} \pi = \{ j_0 \gamma : \pi \circ \gamma \text{ an immersion} \} \subset \mathring{T}_m E$

Put $J_m^{\mathrm{T}} \pi = \rho(\mathring{T}_m^{\mathrm{T}} \pi) \subset J_m E$

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First-order jets of sections

 $\pi: E \to M$ fibration

 $\mathring{T}_m^{\mathrm{T}} \pi = \{j_0 \gamma : \pi \circ \gamma \text{ an immersion}\} \subset \mathring{T}_m E$

Put $J_m^{\mathrm{T}} \pi = \rho(\mathring{T}_m^{\mathrm{T}} \pi) \subset J_m E$

Also define the manifold of jets of local sections

 $J\pi = \{j_x \sigma : x \in W \subset M, \quad \sigma : W \to E, \quad \pi \circ \sigma = \mathrm{id}\}$

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Map $J\pi \rightarrow J_m^{\mathrm{T}}\pi$ by

$$j_x \sigma \mapsto [j_0(\sigma \circ \psi^{-1})]$$

where ψ is any chart defined around $x \in M$ with $\psi(x) = 0 \in \mathbb{R}^m$.

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Map $J\pi \rightarrow J_m^{\mathrm{T}}\pi$ by

$$j_x \sigma \mapsto [j_0(\sigma \circ \psi^{-1})]$$

where ψ is any chart defined around $x \in M$ with $\psi(x) = 0 \in \mathbb{R}^m$. This is a well-defined diffeomorphism.

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Double velocities

The double velocity manifold is

 $T_m T_m E = \{j_0 \tilde{\gamma} : \tilde{\gamma} \text{ an } m \text{-curve in } T_m E\}$

and is a double vector bundle

 $\tau_{m(T_m E)}, T_m \tau_{mE} : T_m T_m E \rightarrow T_m E$.



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Submanifolds $T_m \mathring{T}_m E$, $\mathring{T}_m T_m E$, $\mathring{T}_m \mathring{T}_m E$,

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Vertical double velocity manifold

$$V_m \tau_{mE} = \{ j_0 \tilde{\gamma} : T_m \tau_{mE} (j_0 \tilde{\gamma}) = 0 \}$$

$$\cong au_{mE}^* TE \otimes_{T_mE} \bigotimes^2 \mathbb{R}^{m*}$$

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Prolongations and semiprolongations

If γ is an *m*-curve in *E* then $\tilde{\jmath}\gamma$,

$$\tilde{\jmath} \gamma(t) = j_t \gamma = j_0(\gamma \circ \mathsf{t}_t)$$

 $(t_t : \mathbb{R}^m \to \mathbb{R}^m \text{ is the translation map } t_t(s) = t + s) \text{ is an } m$ -curve in $T_m E$, the prolongation of γ .

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If γ is an immersion then so is its prolongation $\tilde{\jmath}\gamma$.

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Prolongations and semiprolongations

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If γ is an immersion then so is its prolongation $\tilde{\jmath}\gamma$.

An *m*-curve \tilde{y} in $T_m E$ is a prolongation if there is an *m*-curve y in *E* with $\tilde{y} = \tilde{j}y$.

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Prolongations and semiprolongations

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$$\tilde{\jmath} \gamma(t) = j_t \gamma = j_0(\gamma \circ \mathsf{t}_t)$$

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If γ is an immersion then so is its prolongation $\tilde{\jmath}\gamma$.

An *m*-curve \tilde{y} in $T_m E$ is a prolongation if there is an *m*-curve y in E with $\tilde{y} = \tilde{j}y$. If \tilde{y} is a prolongation then $\tilde{y} = \tilde{j}(\tau_{mE} \circ \tilde{y})$.
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Prolongations and semiprolongations

If γ is an *m*-curve in *E* then $\tilde{\jmath}\gamma$,

$$\tilde{\jmath} \gamma(t) = j_t \gamma = j_0(\gamma \circ \mathsf{t}_t)$$

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If γ is an immersion then so is its prolongation $\tilde{\jmath}\gamma$.

An *m*-curve \tilde{y} in $T_m E$ is a prolongation if there is an *m*-curve y in E with $\tilde{y} = \tilde{j}y$. If \tilde{y} is a prolongation then $\tilde{y} = \tilde{j}(\tau_{mE} \circ \tilde{y})$.

An *m*-curve $\tilde{\gamma}$ in $T_m E$ is a semiprolongation if

$$\tilde{\gamma}(0) = \tilde{j}(\tau_{mE} \circ \tilde{\gamma})(0) = j_0(\tau_{mE} \circ \tilde{\gamma}).$$

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Semiholonomic velocities

A double velocity $j_0 \tilde{y} \in T_m T_m E$ is semiholonomic if some representative *m*-curve \tilde{y} is a semiprolongation.



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Semiholonomic velocities

A double velocity $j_0 \tilde{y} \in T_m T_m E$ is semiholonomic if some representative *m*-curve \tilde{y} is a semiprolongation. (Then every representative \tilde{y} is a semiprolongation.)

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Semiholonomic velocities

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 $j_0 ilde{\gamma}$ is semiholonomic exactly when

$$\tau_{m(T_m E)}(j_0 \tilde{\gamma}) = T_m \tau_{m E}(j_0 \tilde{\gamma}) \in T_m E.$$

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Semiholonomic velocities

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 $j_0 ilde{\gamma}$ is semiholonomic exactly when

$$au_{m(T_m E)}(j_0 \tilde{\gamma}) = T_m \tau_{mE}(j_0 \tilde{\gamma}) \in T_m E.$$

The submanifold $\hat{T}_m^2 E = \{j_0 \tilde{\gamma} \in T_m T_m E, \text{semiholonomic}\}\$ defines an affine sub-bundle of the vector bundle $\tau_{m(T_m E)} : T_m T_m E \to E$, modelled on the vector bundle

$$V_m \tau_{mE} \cong \tau_{mE}^* TE \otimes_{T_m E} \bigotimes^2 \mathbb{R}^{m*} \to T_m E.$$

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The exchange map

A map ψ : $O \times O \rightarrow E$ is a double *m*-curve.



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The exchange map

A map $\psi: O \times O \rightarrow E$ is a double *m*-curve. For each $s \in O$

 $\psi_s: O \to E, \qquad \psi_s(t) = \psi(s, t)$

is an *m*-curve in *E*, so that $j_0\psi_s \in T_mE$.

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The exchange map

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is an *m*-curve in *E*, so that $j_0\psi_s \in T_mE$.

Thus $s \mapsto j_0 \psi_s$ is an *m*-curve in $T_m E$, so that

 $j_0(s \mapsto j_0\psi_s) \in T_m T_m E$.

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is an *m*-curve in *E*, so that $j_0\psi_s \in T_mE$.

Thus $s \mapsto j_0 \psi_s$ is an *m*-curve in $T_m E$, so that

$$j_0(s \mapsto j_0\psi_s) \in T_m T_m E$$
.

The exchange map $e: T_m T_m E \to T_m T_m E$ is well-defined by $\psi \mapsto \hat{\psi}$ where $\hat{\psi}(t, s) = \psi(s, t)$.

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First-order structures

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Holonomic velocities

A double velocity $j_0 \tilde{y} \in T_m T_m E$ is holonomic if some representative *m*-curve \tilde{y} is a prolongation.



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Holonomic velocities

A double velocity $j_0 \tilde{\gamma} \in T_m T_m E$ is holonomic if some representative *m*-curve $\tilde{\gamma}$ is a prolongation. (But *not* every representative $\tilde{\gamma}$ is a prolongation.)

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Holonomic velocities

A double velocity $j_0 \tilde{\gamma} \in T_m T_m E$ is holonomic if some representative *m*-curve $\tilde{\gamma}$ is a prolongation. (But *not* every representative $\tilde{\gamma}$ is a prolongation.)

 $j_0\tilde{y}$ is holonomic exactly when it is fixed by the exchange map, $e(j_0\tilde{y}) = j_0\tilde{y}$.

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Holonomic velocities

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 $j_0\tilde{\gamma}$ is holonomic exactly when it is fixed by the exchange map, $e(j_0\tilde{\gamma}) = j_0\tilde{\gamma}$.

The submanifold $T_m^2 E = \{j_0 \tilde{y} \in T_m T_m E, \text{holonomic}\}$ defines an affine sub-bundle of the vector bundle $\tau_{m(T_m E)} : T_m T_m E \to E$, modelled on the vector bundle

$$V_m^{\vee} \tau_{mE} \cong \tau_{mE}^* TE \otimes_{T_m E} S^2 \mathbb{R}^{m*} \to T_m E.$$

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Holonomic velocities

A double velocity $j_0 \tilde{\gamma} \in T_m T_m E$ is holonomic if some representative *m*-curve $\tilde{\gamma}$ is a prolongation. (But *not* every representative $\tilde{\gamma}$ is a prolongation.)

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$$V_m^{\vee} \tau_{mE} \cong \tau_{mE}^* TE \otimes_{T_m E} S^2 \mathbb{R}^{m*} \to T_m E.$$

The map $\{j_0^2\gamma\} \to T_m^2 E, \, j_0^2\gamma \mapsto j_0(\tilde{\jmath}\gamma)$ is a bijection.

The double group

The holonomic projection and the curvature

Every prolongation is a semiprolongation,

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The holonomic projection and the curvature

Every prolongation is a semiprolongation, so every holonomic double velocity is semiholonomic: $T_m^2 E \subset \hat{T}_m^2 E$ as an affine sub-bundle.

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The holonomic projection and the curvature

Every prolongation is a semiprolongation, so every holonomic double velocity is semiholonomic: $T_m^2 E \subset \hat{T}_m^2 E$ as an affine sub-bundle.

Vertical double velocities have symmetric and skew-symmetric components: $V_m \tau_{mE} \cong V_m^{\vee} \tau_{mE} \oplus_{T_m E} V_m^{\wedge} \tau_{mE}$,

$$V_m^{\vee} \tau_{mE} \cong \tau_{mE}^* TE \otimes_{T_m E} S^2 \mathbb{R}^{m*}$$
$$V_m^{\wedge} \tau_{mE} \cong \tau_{mE}^* TE \otimes_{T_m E} \bigwedge^2 \mathbb{R}^{m*}$$

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$$V_m^{\wedge} \tau_{mE} \cong \tau_{mE}^* TE \otimes_{T_m E} \bigwedge^2 \mathbb{R}^{m*}$$

Furthermore,

$$T_m^2 E \oplus_{T_m E} V_m^\wedge \tau_{m E} \to \hat{T}_m^2 E$$

is an isomorphism of affine bundles over $T_m E$.

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The holonomic projection and the curvature

Every prolongation is a semiprolongation, so every holonomic double velocity is semiholonomic: $T_m^2 E \subset \hat{T}_m^2 E$ as an affine sub-bundle.

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Furthermore,

$$T_m^2 E \oplus_{T_m E} V_m^\wedge \tau_{m E} \to \hat{T}_m^2 E$$

is an isomorphism of affine bundles over $T_m E$.

The skew-symmetric component of a semiholonomic double velocity is called its curvature.

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The double structure for regular double velocities



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The double structure for regular double velocities



Put

$$\mathring{T}_m^2 E = \hat{T}_m^2 E \cap T_m \mathring{T}_m E, \qquad \mathring{T}_m^2 E = T_m^2 E \cap T_m \mathring{T}_m E$$

then

$$\mathring{T}_m^2 E \subset \mathring{T}_m^2 E \subset \mathring{T}_m^{\mathrm{T}} \mathring{\tau}_{mE}.$$

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The velocity group

The velocity manifold $T_m L_m$ of the jet group L_m is itself a Lie group.

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The velocity group

The velocity manifold $T_m L_m$ of the jet group L_m is itself a Lie group.

If σ_1 , σ_2 are *m*-curves in L_m then $j_0\sigma_1, j_0\sigma_2 \in T_mL_m$, and

$$j_0\sigma_1 \cdot j_0\sigma_2 = j_0(\sigma_1 \cdot \sigma_2)$$

where $\sigma_1 \cdot \sigma_2$ is the *m*-curve $t \mapsto \sigma_1(t)\sigma_2(t)$.

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The velocity group

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If σ_1 , σ_2 are *m*-curves in L_m then $j_0\sigma_1, j_0\sigma_2 \in T_mL_m$, and

$$j_0\sigma_1 \cdot j_0\sigma_2 = j_0(\sigma_1 \cdot \sigma_2)$$

where $\sigma_1 \cdot \sigma_2$ is the *m*-curve $t \mapsto \sigma_1(t)\sigma_2(t)$.

(This construction applies to any Lie group, and is a generalisation of the tangent group construction.)

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Double velocities to double contact elements

The free right action of L_m on $\mathring{T}_m E$,

 $\alpha: L_m \times \mathring{T}_m E \to \mathring{T}_m E \,, \qquad \alpha(j_0 \phi, j_0 \gamma) = j_0(\gamma \circ \phi)$

gives rise to a free right action of $T_m L_m$ on $T_m \mathring{T}_m E$,

 $\tilde{\alpha}: T_m L_m \times T_m \mathring{T}_m E \to T_m \mathring{T}_m E \,, \qquad \tilde{\alpha}(j_0 \sigma, j_0 \tilde{\gamma}) = j_0(\alpha \circ (\sigma, \tilde{\gamma}) \circ \Delta)$

where σ is an *m*-curve in L_m , and $\Delta : \mathbb{R}^m \to \mathbb{R}^m \times \mathbb{R}^m$ is the diagonal inclusion map.

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Double velocities to double contact elements

The free right action of L_m on $\mathring{T}_m E$,

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gives rise to a free right action of $T_m L_m$ on $T_m \mathring{T}_m E$,

 $\tilde{\alpha}: T_m L_m \times T_m \mathring{T}_m E \to T_m \mathring{T}_m E \,, \qquad \tilde{\alpha}(j_0 \sigma, j_0 \tilde{\gamma}) = j_0(\alpha \circ (\sigma, \tilde{\gamma}) \circ \Delta)$

where σ is an *m*-curve in L_m , and $\Delta : \mathbb{R}^m \to \mathbb{R}^m \times \mathbb{R}^m$ is the diagonal inclusion map.

The quotient $T_m \mathring{T}_m E / T_m L_m$ may be identified with the velocity manifold $T_m J_m E$.

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Double velocities to double contact elements

The free right action of L_m on $\mathring{T}_m E$,

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where σ is an *m*-curve in L_m , and $\Delta : \mathbb{R}^m \to \mathbb{R}^m \times \mathbb{R}^m$ is the diagonal inclusion map.

The quotient $T_m \mathring{T}_m E / T_m L_m$ may be identified with the velocity manifold $T_m J_m E$.

 L_m now acts freely on the open submanifold $\mathring{T}_m J_m E$, giving the quotient $J_m J_m E$.

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The double group

The right action of the jet group L_m on the velocity group $T_m L_m$

$$(j_0\phi, j_0\sigma) \mapsto j_0(\sigma \circ \phi)$$

is an action by automorphisms.

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The double group

The right action of the jet group L_m on the velocity group $T_m L_m$

$$(j_0\phi, j_0\sigma) \mapsto j_0(\sigma \circ \phi)$$

is an action by automorphisms.

Define the double group D_m to be the semidirect product $L_m \rtimes T_m L_m$.

An element of D_m is a pair $(j_0\phi, j_0\sigma)$ where ϕ is a local diffeomorphism of R^m fixing zero and σ is an *m*-curve in L_m .

The double group

Double *m*-curves and the double group Let $\psi : O \times O \rightarrow \mathbb{R}^m$ be a double *m*-curve. Put

 $\tilde{\psi}_s(t) = \psi(s,t) - \psi(s,0), \qquad \tilde{\psi}_t(s) = \psi(s,t) - \psi(0,t).$



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Double *m*-curves and the double group Let $\psi : O \times O \rightarrow \mathbb{R}^m$ be a double *m*-curve. Put

$$\tilde{\psi}_s(t) = \psi(s,t) - \psi(s,0), \qquad \tilde{\psi}_t(s) = \psi(s,t) - \psi(0,t).$$

Suppose both $\tilde{\psi}_s$ and $\tilde{\psi}_t$ are local diffeomorphisms of \mathbb{R}^m for all s, t, so that $j_0 \tilde{\psi}_s, j_0 \tilde{\psi}_t \in L_m$. Then $t \mapsto j_0 \tilde{\psi}_t$ is an *m*-curve in L_m .

Any element $(j_0\phi, j_0\sigma) \in D_m$ may therefore be written as

$$(j_0\tilde{\psi}_{s=0}, j_0(t\mapsto j_0\tilde{\psi}_t)).$$

The double group

Double *m*-curves and the double group Let $\psi : O \times O \rightarrow \mathbb{R}^m$ be a double *m*-curve. Put

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Any element $(j_0\phi, j_0\sigma) \in D_m$ may therefore be written as

$$(j_0\tilde{\psi}_{s=0}, j_0(t\mapsto j_0\tilde{\psi}_t))$$
.

Two such double *m*-curves ψ , χ determine the same element of D_m when

$$\frac{\partial \psi}{\partial s} = \frac{\partial \chi}{\partial s}, \qquad \frac{\partial \psi}{\partial t} = \frac{\partial \chi}{\partial t}, \qquad \frac{\partial^2 \psi}{\partial s \,\partial t} = \frac{\partial^2 \chi}{\partial s \,\partial t}.$$

The double group

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Holonomic and semiholonomic subgroups

An element $(j_0\phi, j_0\sigma) \in D_m$ is holonomic if $\sigma = \tilde{j}\phi$ (so that the element is $(j_0\phi, j_0^2\phi)$).

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Holonomic and semiholonomic subgroups

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 $\{(j_0\phi, j_0^2\phi)\}$ is a closed Lie subgroup of D_m isomorphic to the second order jet group L_m^2 .

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Holonomic and semiholonomic subgroups

An element $(j_0\phi, j_0\sigma) \in D_m$ is holonomic if $\sigma = \tilde{j}\phi$ (so that the element is $(j_0\phi, j_0^2\phi)$).

 $\{(j_0\phi, j_0^2\phi)\}$ is a closed Lie subgroup of D_m isomorphic to the second order jet group L_m^2 .

An element $(j_0\phi, j_0\sigma) \in D_m$ is semiholonomic if $\sigma(0) = j_0\phi$ (so that the element is $(\sigma(0), j_0\sigma)$).

Holonomic and semiholonomic subgroups

An element $(j_0\phi, j_0\sigma) \in D_m$ is holonomic if $\sigma = \tilde{j}\phi$ (so that the element is $(j_0\phi, j_0^2\phi)$).

 $\{(j_0\phi, j_0^2\phi)\}$ is a closed Lie subgroup of D_m isomorphic to the second order jet group L_m^2 .

An element $(j_0\phi, j_0\sigma) \in D_m$ is semiholonomic if $\sigma(0) = j_0\phi$ (so that the element is $(\sigma(0), j_0\sigma)$).

 $\{(j_0\phi, j_0\sigma)\}$ is a closed Lie subgroup $\hat{L}_m^2 \subset D_m$ diffeomorphic to T_mL_m , but *not* isomorphic as a group.
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The curvature subgroup

There is a map $\vee : D_m \to D_m$ given in terms of double curves by

$$\psi(s,t)\mapsto \frac{1}{2}(\psi(s,t)+\psi(t,s))\,.$$

This restricts to a surjective map $\hat{L}_m^2 \rightarrow L_m^2$.

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Double velocities

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This restricts to a surjective map $\hat{L}_m^2 \rightarrow L_m^2$.

There is an injective map $\mu: L_m \to \hat{L}_m^2$ given by

$$\mu(j_0\phi) = (j_0\phi, j_0(t \mapsto j_0\phi)).$$

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Double velocities

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The curvature subgroup

There is a map $\vee : D_m \to D_m$ given in terms of double curves by

$$\psi(s,t) \mapsto \frac{1}{2}(\psi(s,t) + \psi(t,s)).$$

This restricts to a surjective map $\hat{L}_m^2 \rightarrow L_m^2$.

There is an injective map $\mu: L_m \rightarrow \hat{L}_m^2$ given by

$$\mu(j_0\phi) = (j_0\phi, j_0(t \mapsto j_0\phi)).$$

The curvature subgroup \tilde{L}_m^2 is the semidirect product

$$\tilde{L}_m^2 = \mu(L_m) \rtimes \ker \vee \, .$$

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The double group action

 $\tilde{\alpha} : T_m L_m \times T_m T_m E \to T_m T_m E$, $\tilde{\alpha}(j_0 \sigma, j_0 \tilde{\gamma}) = j_0(\alpha \circ (\sigma, \tilde{\gamma}) \circ \Delta)$ The action is free on $T_m \mathring{T}_m E$, with quotient $T_m J_m E$.



Double velocities

The double group

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The double group action

$$\begin{split} \tilde{\alpha} &: T_m L_m \times T_m T_m E \to T_m T_m E, \\ \tilde{\alpha} &(j_0 \sigma, j_0 \tilde{\gamma}) = j_0 (\alpha \circ (\sigma, \tilde{\gamma}) \circ \Delta) \\ \text{The action is free on } T_m \mathring{T}_m E, \text{ with quotient } T_m J_m E. \end{split}$$

 $\alpha : L_m \times T_m J_m E \to T_m J_m E$, $\alpha(j_0 \phi, j_0 \gamma) = j_0(\gamma \circ \phi)$ The action is free on $\mathring{T}_m J_m E$, with quotient $J_m J_m E$.

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The double group action

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 The action is free on $T_m \mathring{T}_m E$, with quotient $T_m J_m E$.

 $\alpha : L_m \times T_m J_m E \to T_m J_m E$, $\alpha(j_0 \phi, j_0 \gamma) = j_0(\gamma \circ \phi)$ The action is free on $\mathring{T}_m J_m E$, with quotient $J_m J_m E$.

The double group has an action

$$\bar{\alpha}: D_m \times T_m T_m E \to T_m T_m E$$
$$\bar{\alpha}((j_0 \phi, j_0 \sigma), j_0 \tilde{\gamma}) = \tilde{\alpha}(j_0 \sigma, \alpha(j_0 \phi, j_0 \tilde{\gamma})).$$

The restriction of the action to $\mathring{T}_m^{\mathrm{T}}\rho$ is free, and the quotient may be identified with $J_m J_m E$.

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The double group action

$$\begin{split} \tilde{\alpha} &: T_m L_m \times T_m T_m E \to T_m T_m E, \\ \tilde{\alpha} &(j_0 \sigma, j_0 \tilde{\gamma}) = j_0 (\alpha \circ (\sigma, \tilde{\gamma}) \circ \Delta) \\ \text{The action is free on } T_m \mathring{T}_m E, \text{ with quotient } T_m J_m E. \end{split}$$

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The double group has an action

$$\bar{\alpha}: D_m \times T_m T_m E \to T_m T_m E$$

$$\bar{\alpha}((j_0 \phi, j_0 \sigma), j_0 \tilde{\gamma}) = \tilde{\alpha}(j_0 \sigma, \alpha(j_0 \phi, j_0 \tilde{\gamma})).$$

The restriction of the action to $\mathring{T}_m^{\mathrm{T}}\rho$ is free, and the quotient may be identified with $J_m J_m E$. We also consider the restriction to $\mathring{T}_m^{\mathrm{T}}\mathring{\tau}_{mE} \subset \mathring{T}_m^{\mathrm{T}}\rho$, with quotient $J_m^{\mathrm{T}}\pi_{mE}$.
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The double structure for contact elements



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Semiholonomic contact elements

Let $\bar{\rho}$ denote the projection $\mathring{T}_m^{\mathrm{T}} \rho \to J_m J_m E$, and also the restricted map $\mathring{T}_m^{\mathrm{T}} \mathring{\tau}_{mE} \to J_m^{\mathrm{T}} \pi_{mE}$.

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Semiholonomic contact elements

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A contact element is semiholonomic if it is of the form $\bar{\rho}(j_0\tilde{\gamma})$ for some $j_0\tilde{\gamma} \in \mathring{T}_m^2 E$.



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Semiholonomic contact elements

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A contact element is semiholonomic if it is of the form $\bar{\rho}(j_0\tilde{\gamma})$ for some $j_0\tilde{\gamma} \in \mathring{T}_m^2 E$.

The submanifold

 $\hat{J}_m^2 E = \{ \bar{\rho}(j_0 \tilde{\gamma}) \text{ semiholonomic} \}$

may be identified with the quotient $\mathring{T}_m^2 E/\hat{L}_m^2$.

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Semiholonomic contact elements

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The submanifold

 $\hat{J}_m^2 E = \{ \bar{\rho}(j_0 \tilde{\gamma}) \text{ semiholonomic} \}$

may be identified with the quotient $\mathring{T}_m^2 E/\hat{L}_m^2$.

 $\hat{J}_m^2 E \to J_m E$ is an affine bundle, modelled on the vector bundle $V_m \mathring{\tau}_{mE} / \hat{L}_m^2 \to J_m E$.

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Holonomic contact elements

A contact element is holonomic if it is of the form $\bar{\rho}(j_0\tilde{\gamma})$ for some $j_0\tilde{\gamma} \in \mathring{T}_m^2 E$.

The submanifold

 $J_m^2 E = \{ \bar{\rho}(j_0 \tilde{\gamma}) \text{ holonomic} \}$

may be identified with the quotient $\mathring{T}_m^2 E/L_m^2$.

 $J_m^2 E \to J_m E$ is an affine bundle, modelled on the vector bundle $V_m^{\vee} \mathring{\tau}_{mE} / L_m^2 \to J_m E$.

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Curvature of semiholonomic contact elements

The decomposition

$$V_m \overset{\circ}{\tau}_{mE} = V_m^{\vee} \overset{\circ}{\tau}_{mE} \oplus V_m^{\wedge} \overset{\circ}{\tau}_{mE}$$

projects to a decomposition

$$V_m \mathring{\tau}_{mE} / \hat{L}_m^2 \cong V_m^{\vee} \mathring{\tau}_{mE} / L_m^2 \oplus V_m^{\wedge} \mathring{\tau}_{mE} / \tilde{L}_m^2 \,.$$

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Curvature of semiholonomic contact elements

The decomposition

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This gives a decomposition of a semiholonomic contact element in $\hat{J}_m^2 E$

as the sum of a holonomic contact element in $J_m^2 E$ and a curvature element in $V_m^{\wedge} \mathring{\tau}_{mE} / \tilde{L}_m^2$.